



Unlock the Future of Railway Inspection



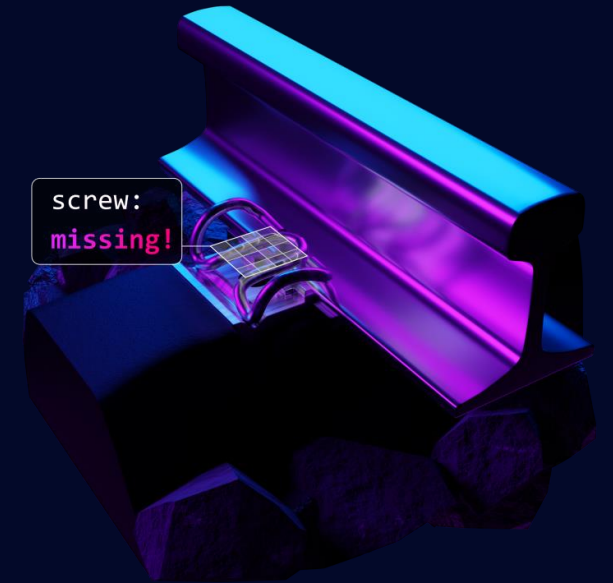
Generate Synthetic Data for Highly Accurate Railway Defect Detection



All-in-One Solutions for Defect Detection, from Data Generation to Model Training



Train AI to Detect any Defects like Fractured or Missing Components. No Real-world Data Needed





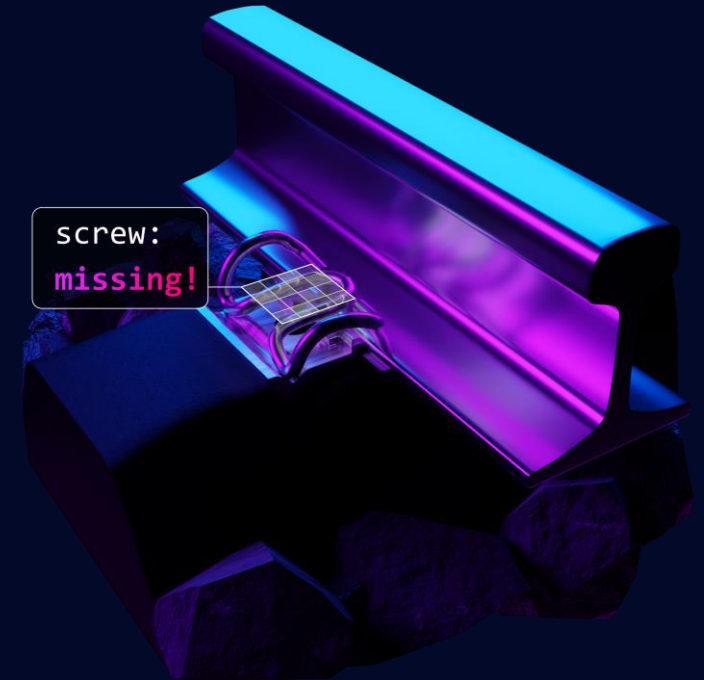
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We unlock unique opportunities

Example



As a **railway infrastructure company**, I want to **detect**

- missing
- fractured
- misaligned

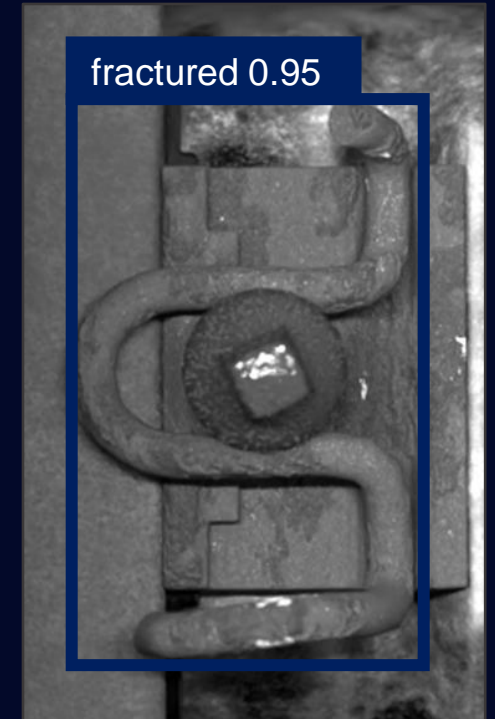
tension clamps on image data.



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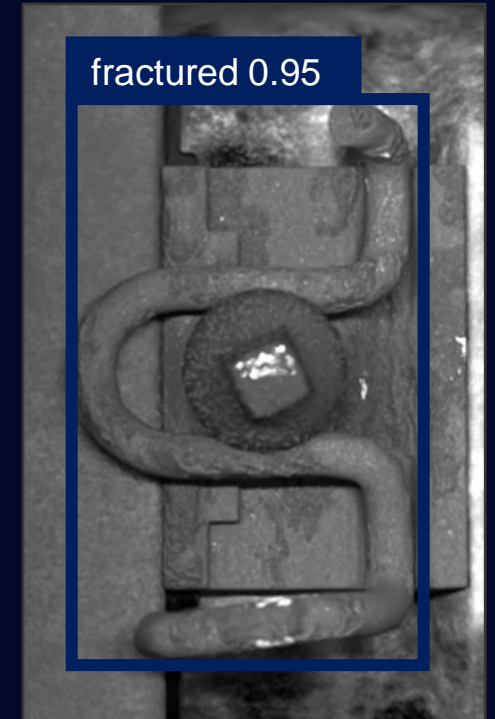


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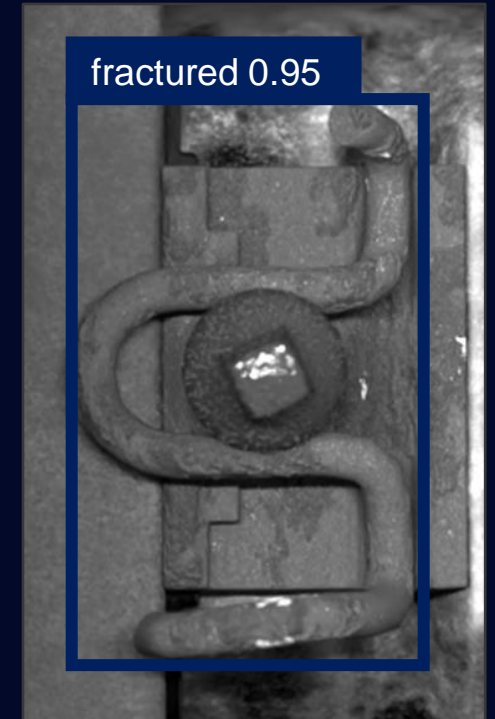


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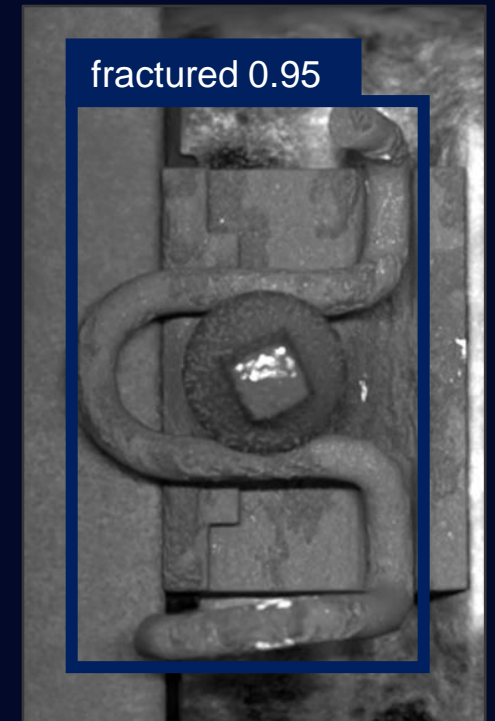
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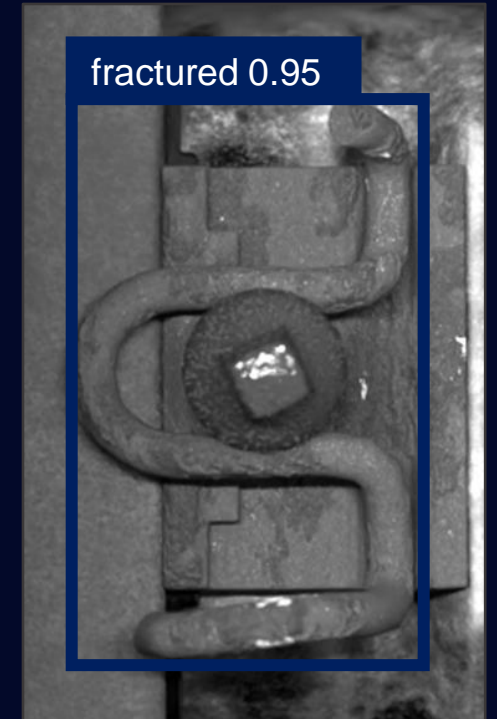
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Solution

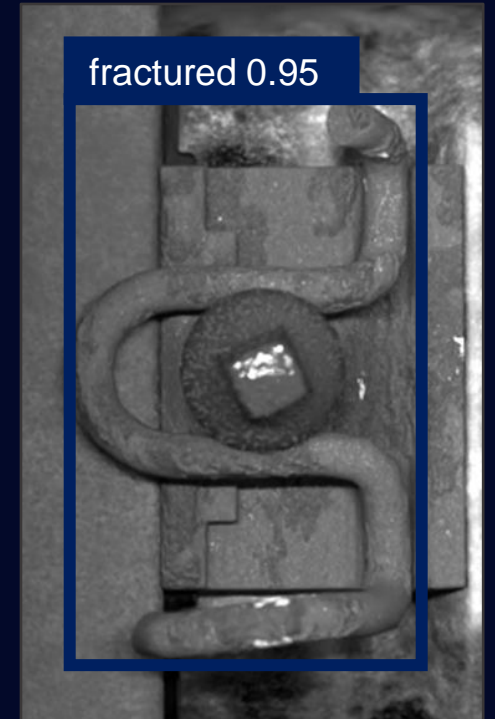


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We at ex-nihilo create them!

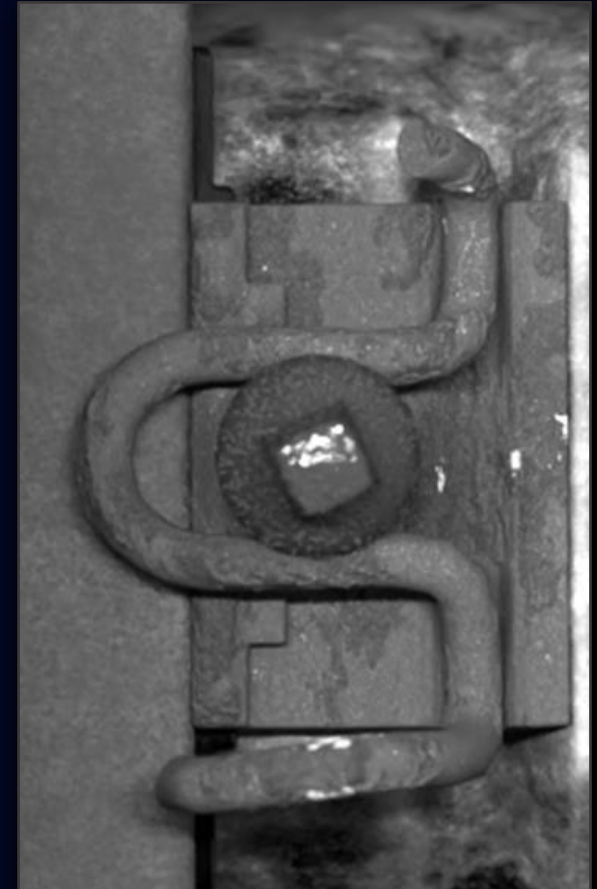


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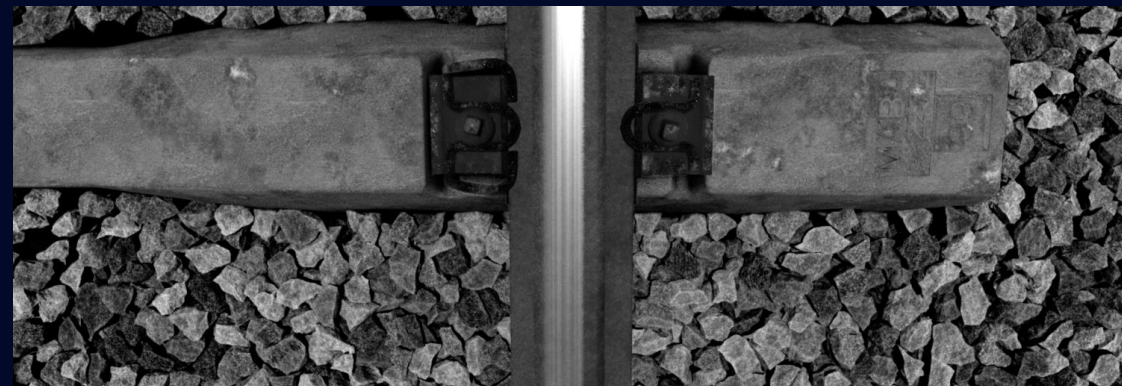
Synthetic image by ex-nihilo

Synthetic Training Data

Fixed Track "feste Fahrbahn PORR"

„W-Oberbau“

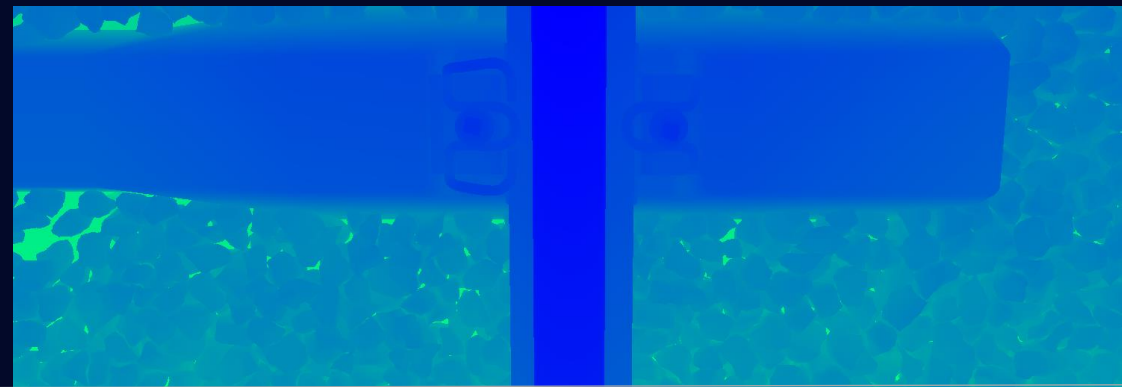
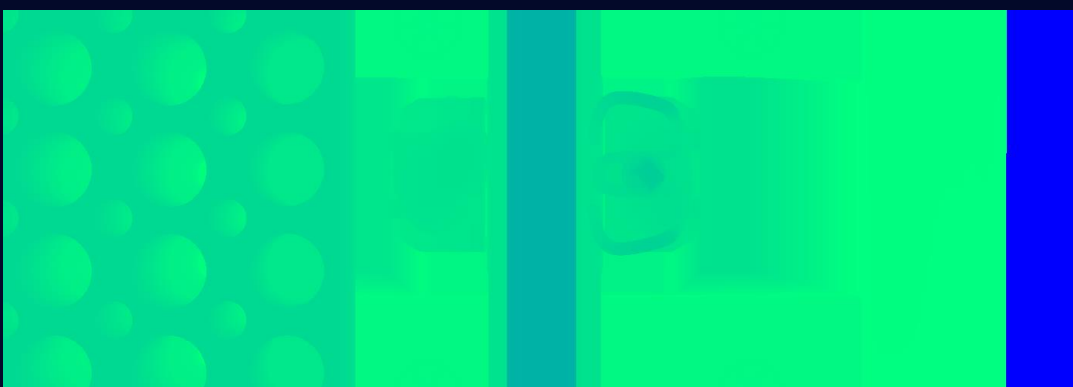
gray



panoptic



depth



In-House Software “Ghegapixel”

Ghgeapixel Dataset Generator

Configuration

System PORR

Dataset Size

10

image width

256

pixel

image height

256

pixel

Generate

☒ Grayscale

☐ Depth Maps


☐ Segmentation Images

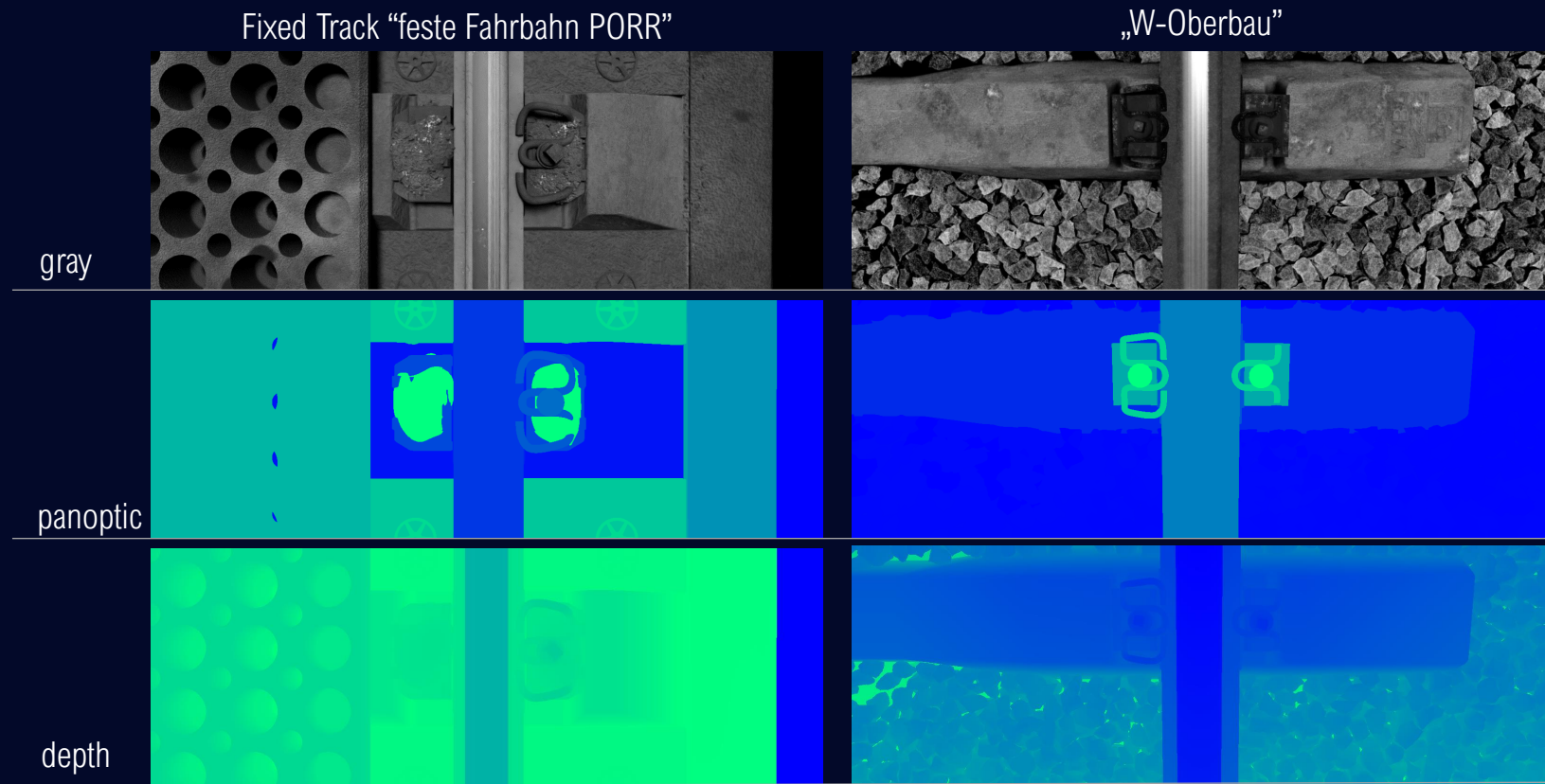
Annotation Format

Supervisely

Estimated render time: 28 minutes

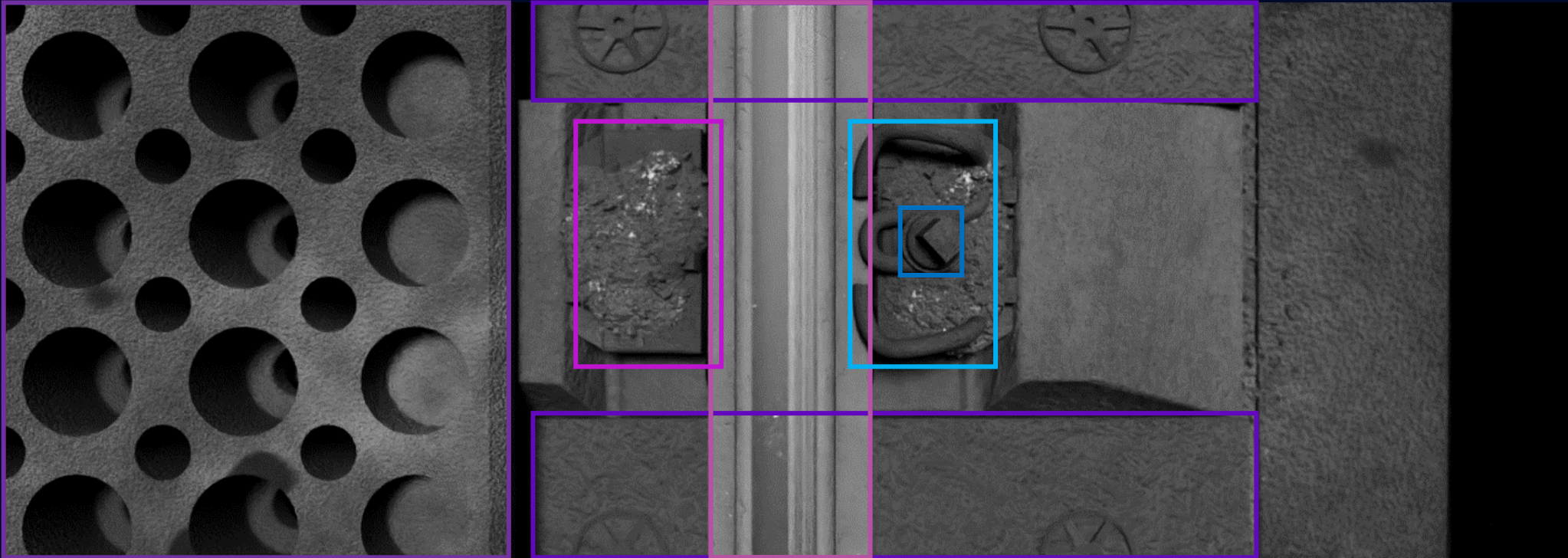
START

Made by  in Vienna.



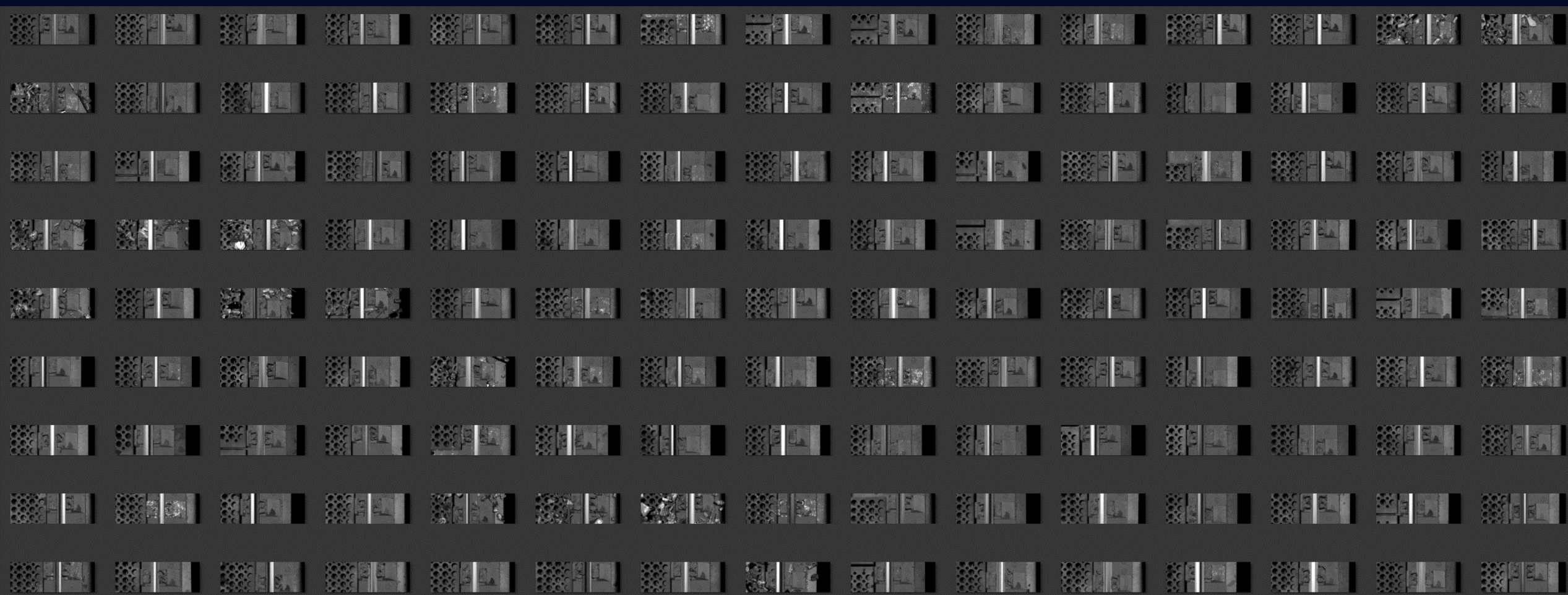


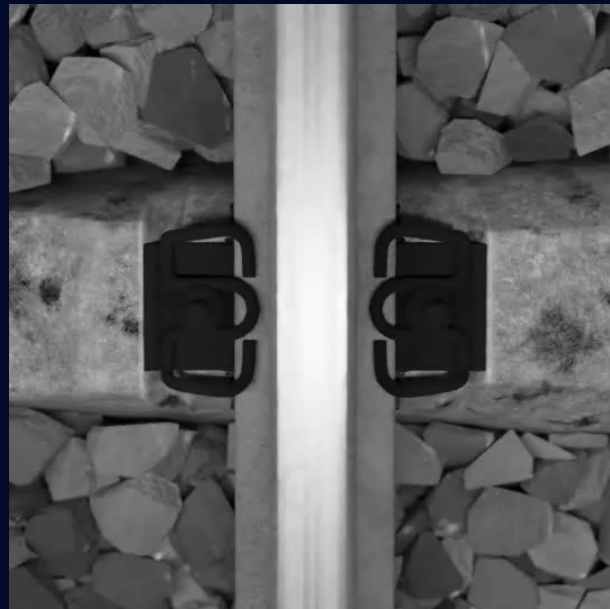
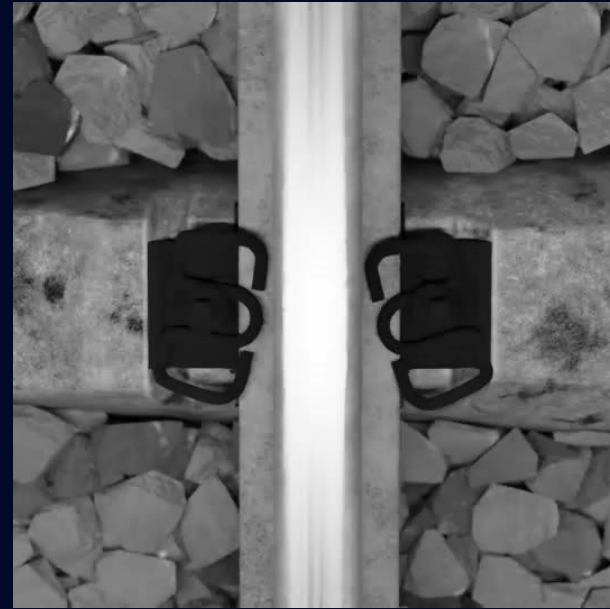
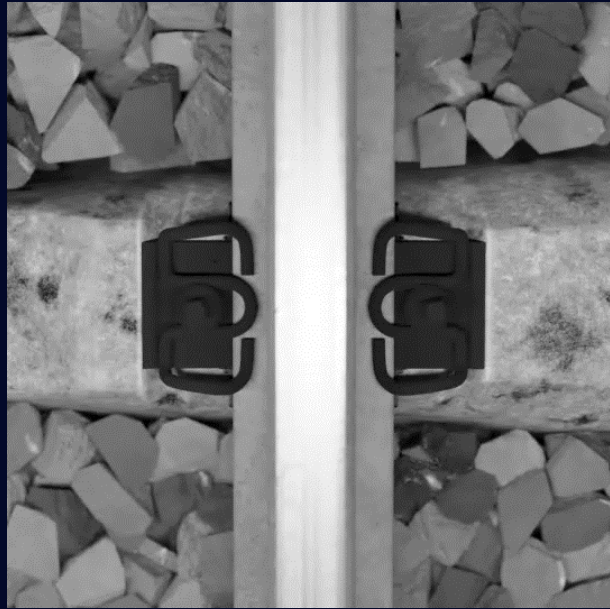
We can create any annotation of any object you like
With any metadata (rotation, placement, attributes like dirty, etc.) you want



In any Format you need (YOLO, MS-COCO, Supervisely, etc.)

Any dataset size you wish





Railway Specific Parameters (just a few)

- Gradation curve of track ballast (Schotter Sieblinie, Körnung)
- Track curve Radius
- Sinusoidal cart motion
- Cart length, Bogie placement, etc.
- Polished rail head

General Parameters (just a few)

- Dirt, Trash, Rust, Moisture, etc.
- Defects, Missing, Misaligned, Fractured components, etc.

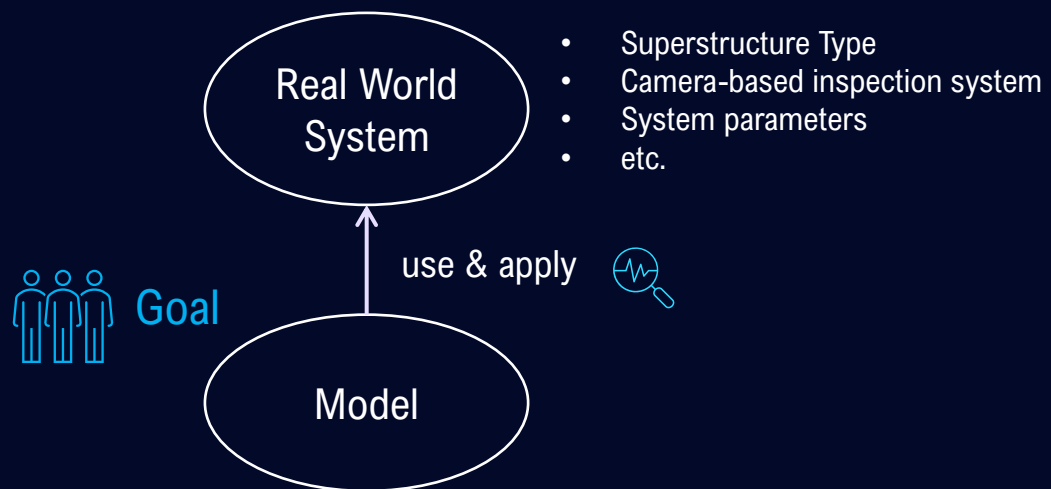


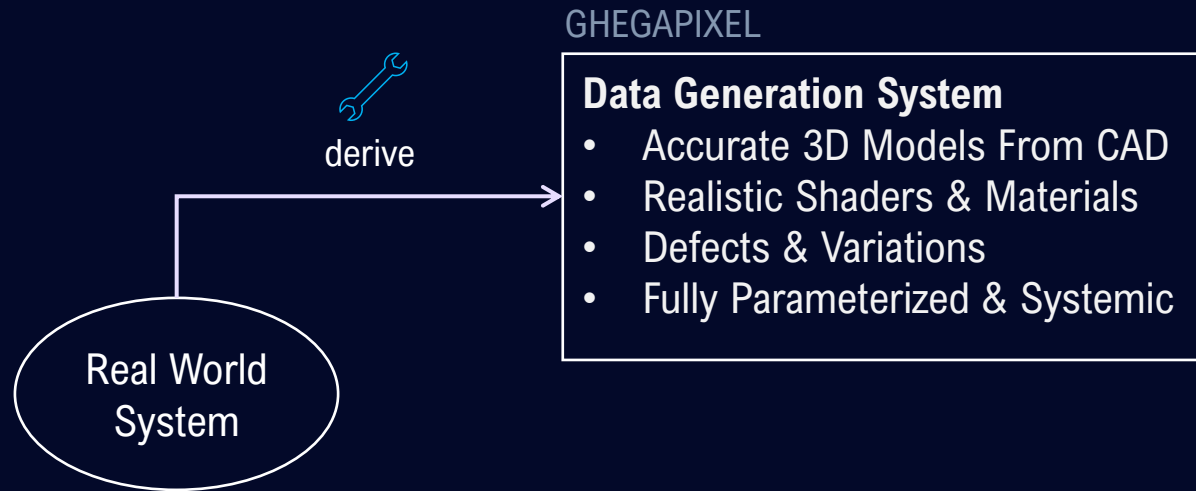
This system allows us to achieve unprecedented levels of accuracy in detection models.

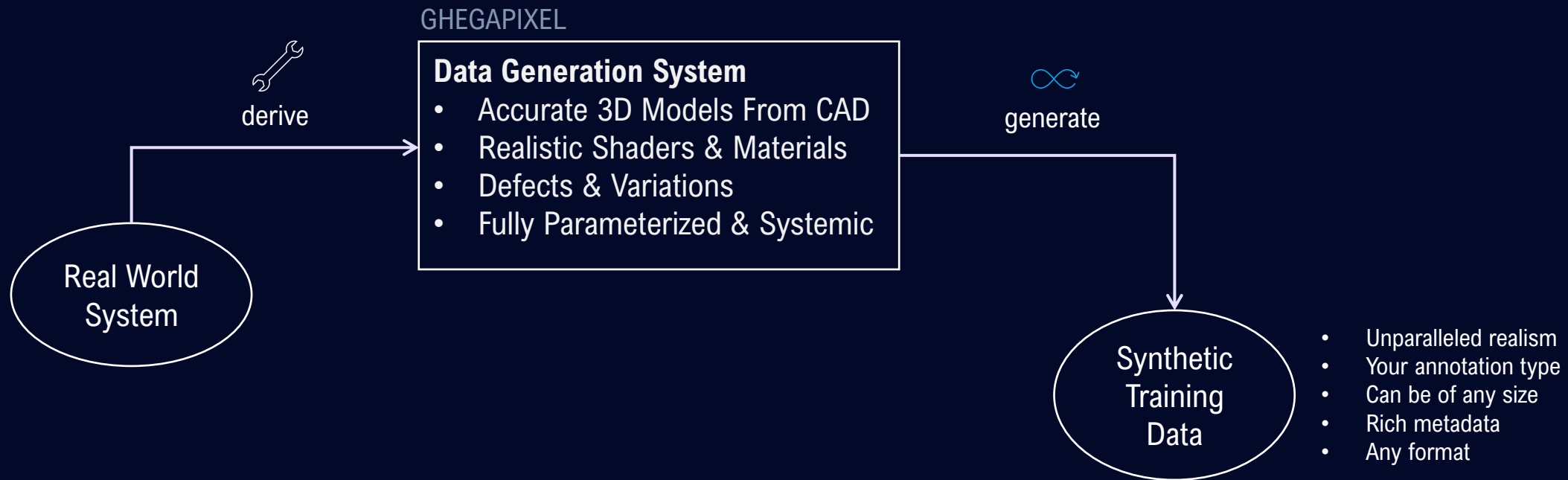
How The ex-nihilo Process

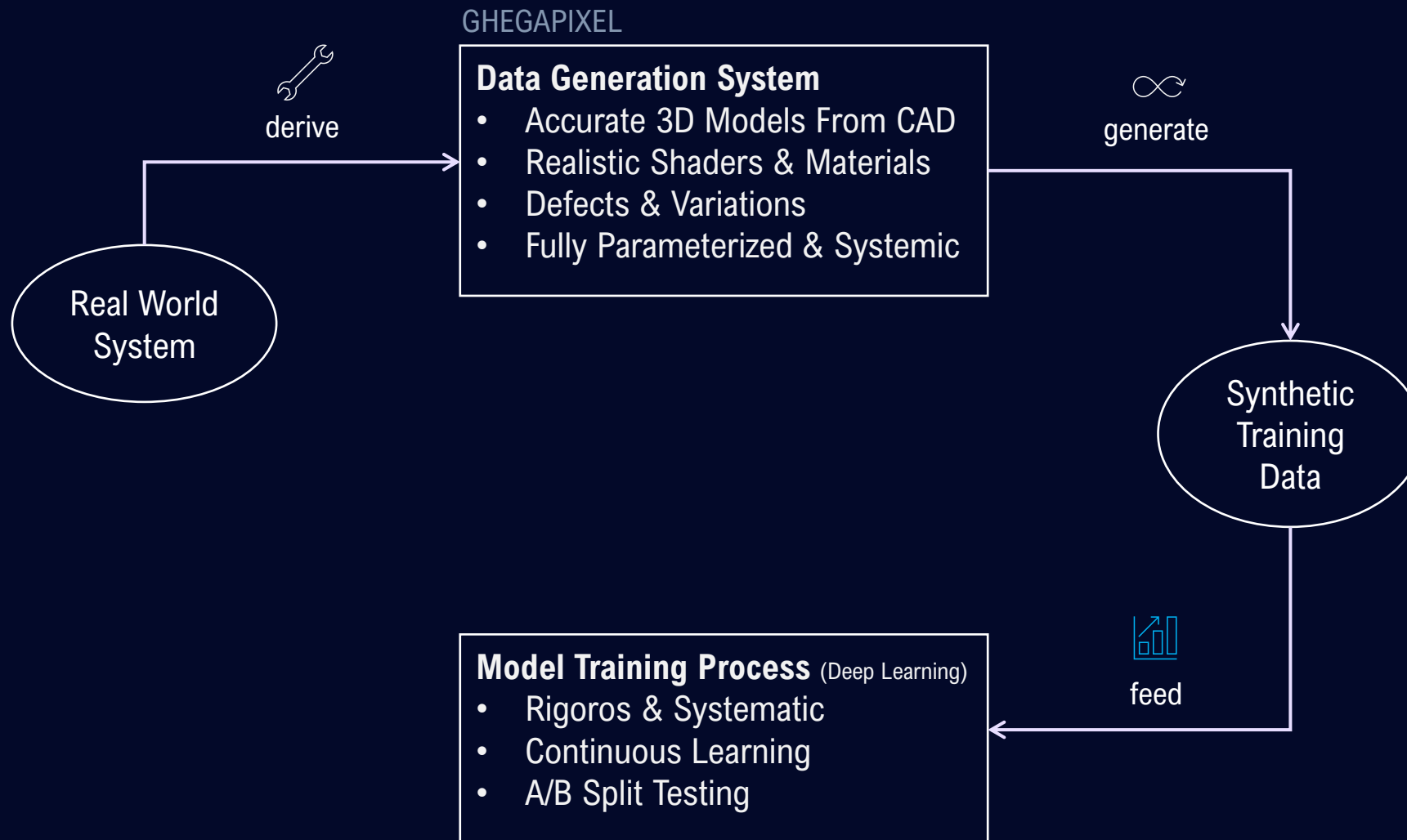
Real World
System

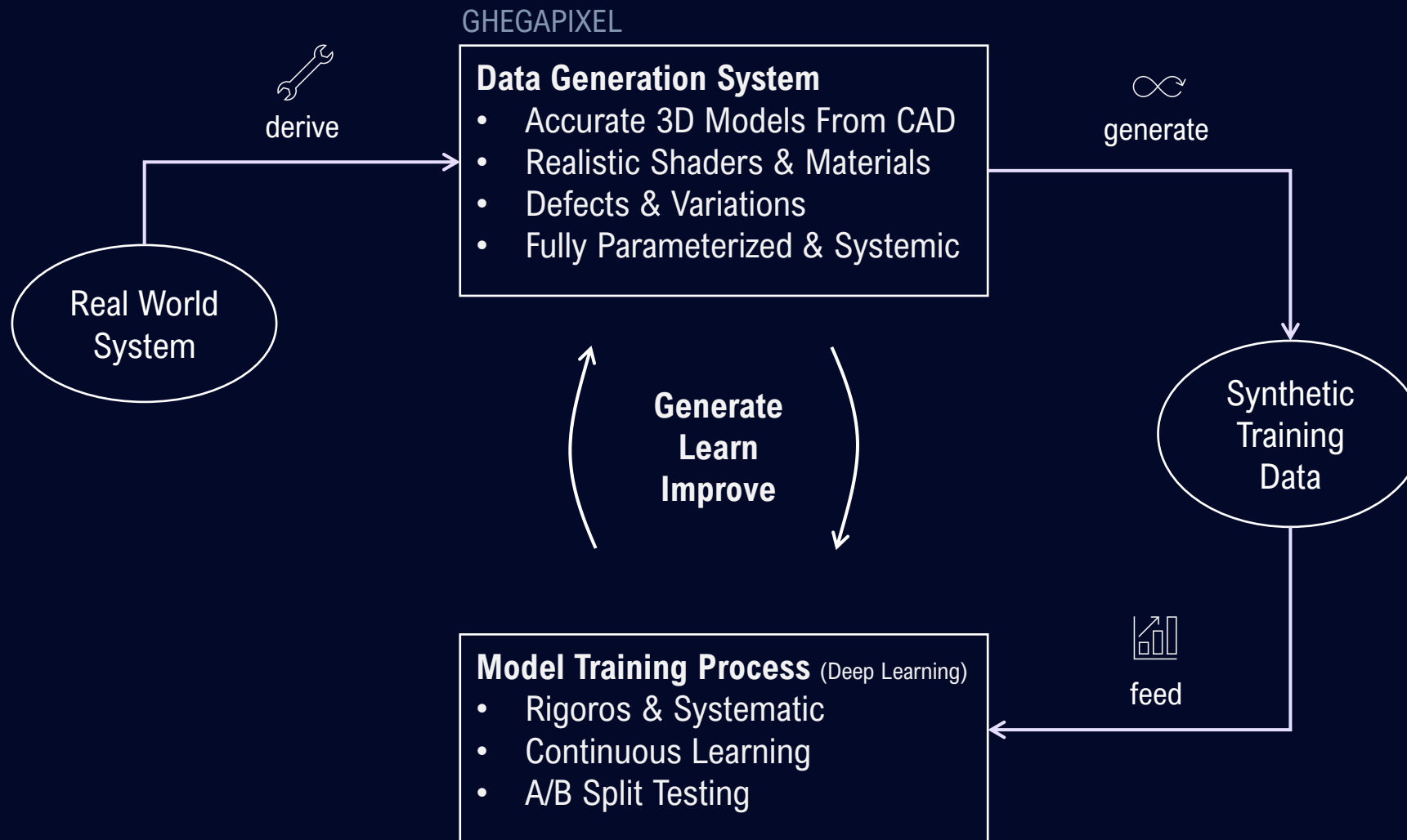
- Superstructure Type
- Camera-based inspection system
- System parameters
- etc.

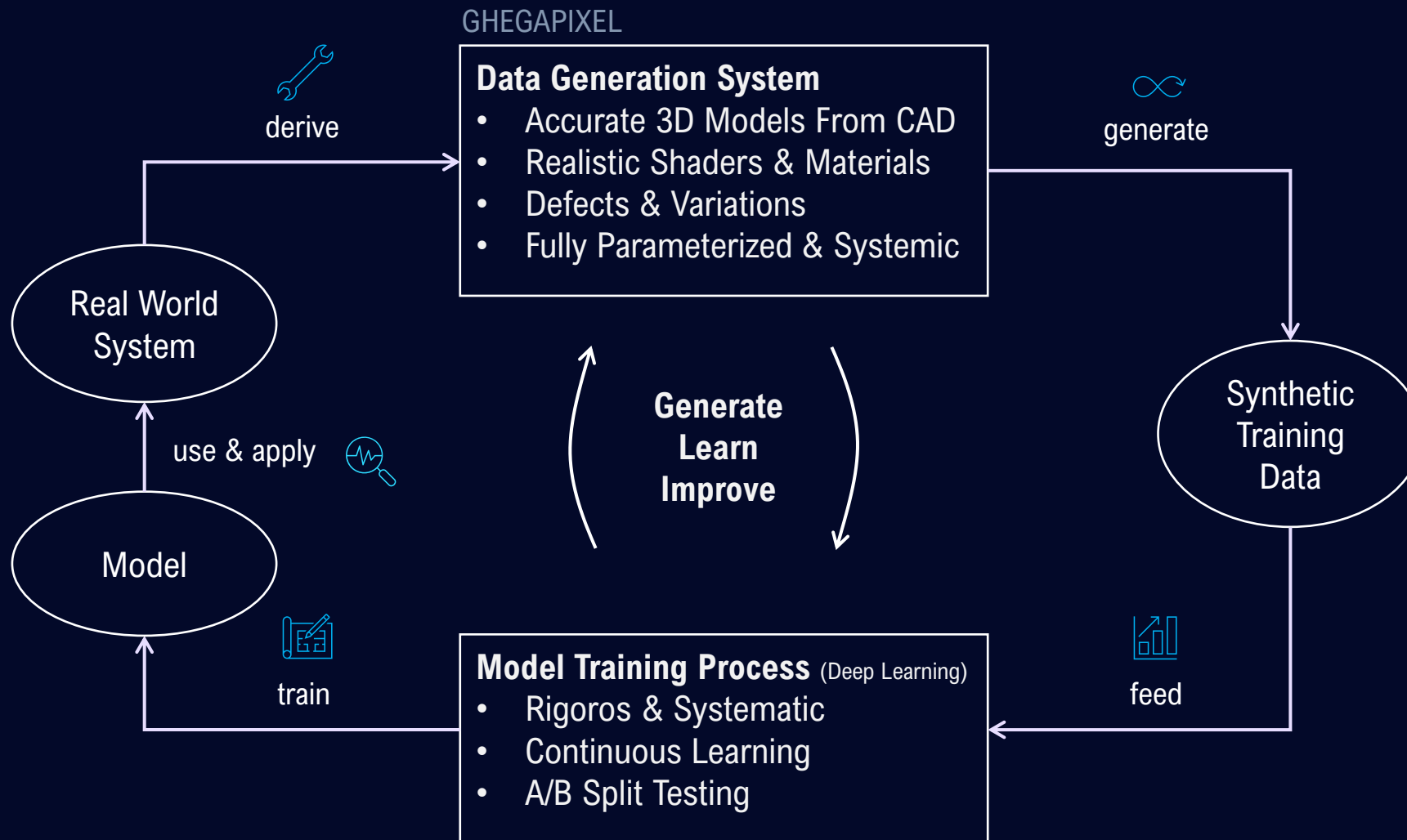


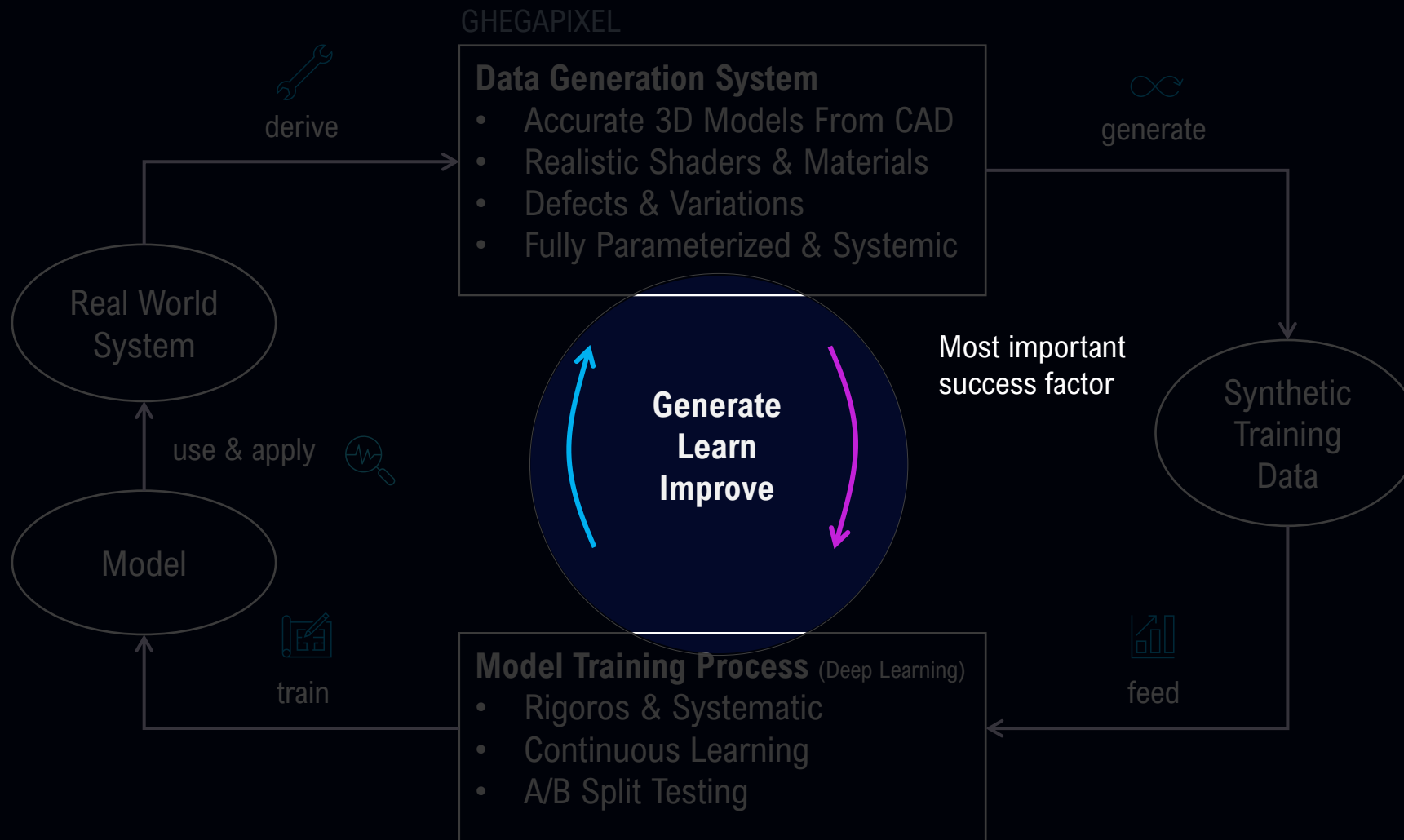




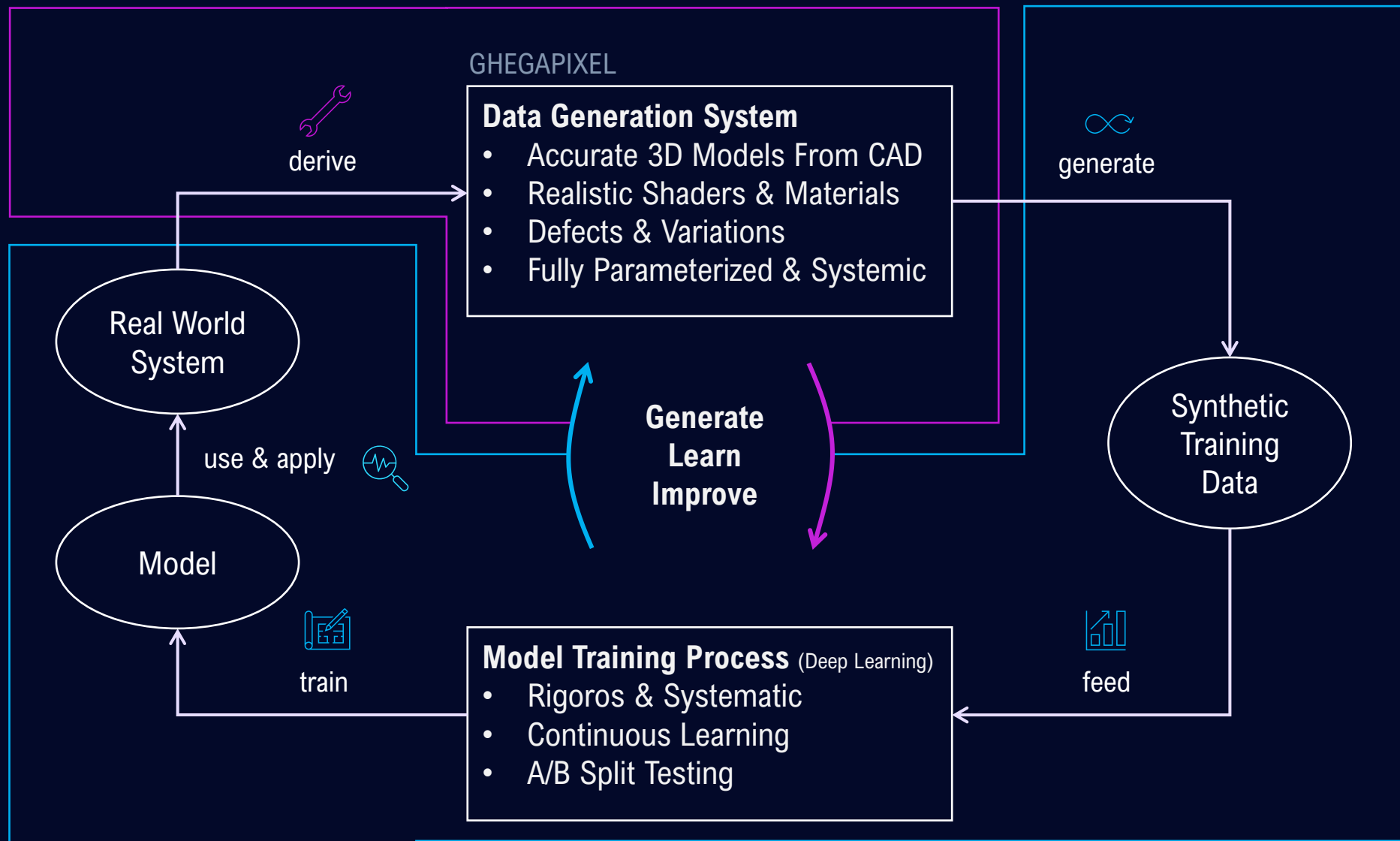




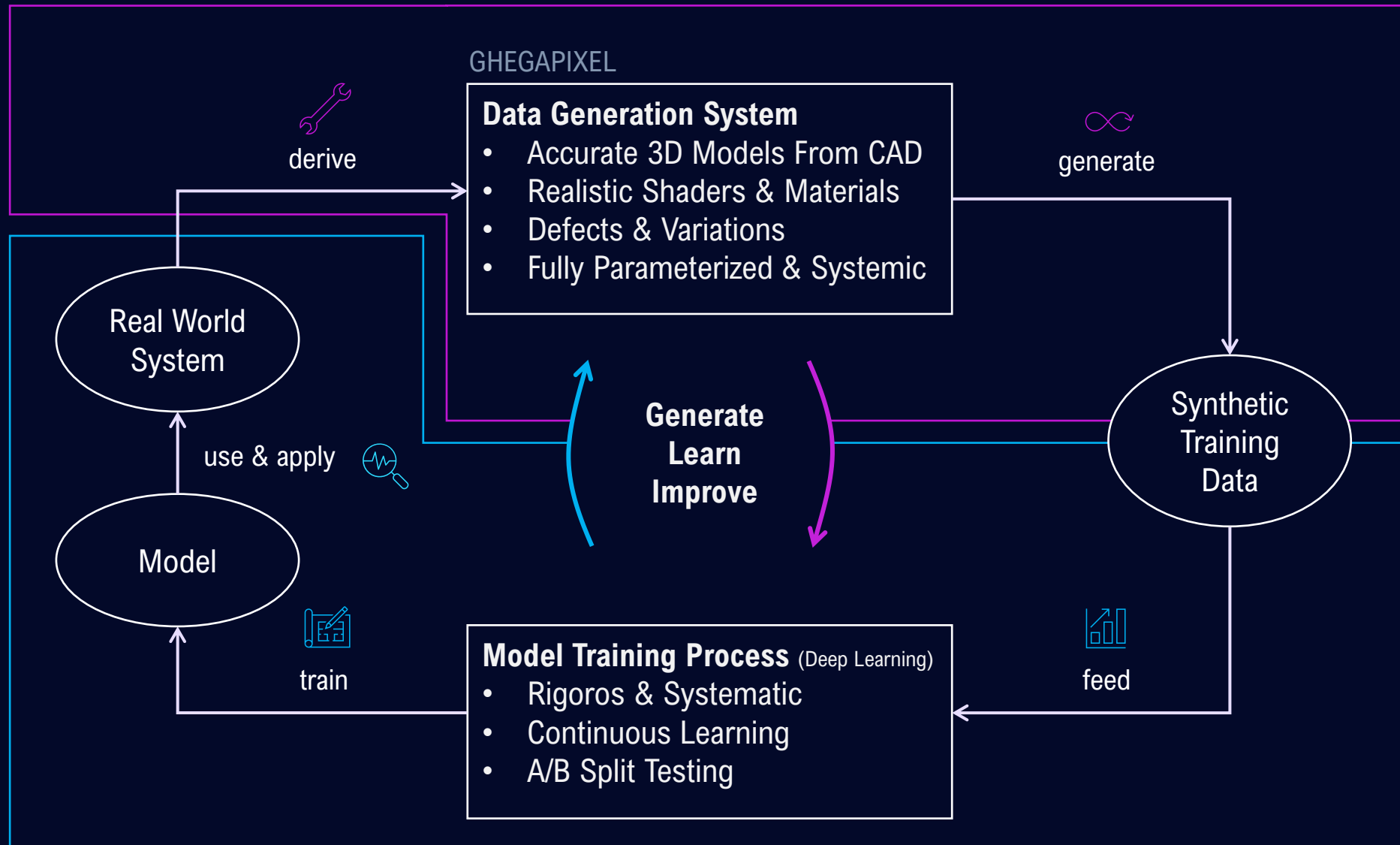




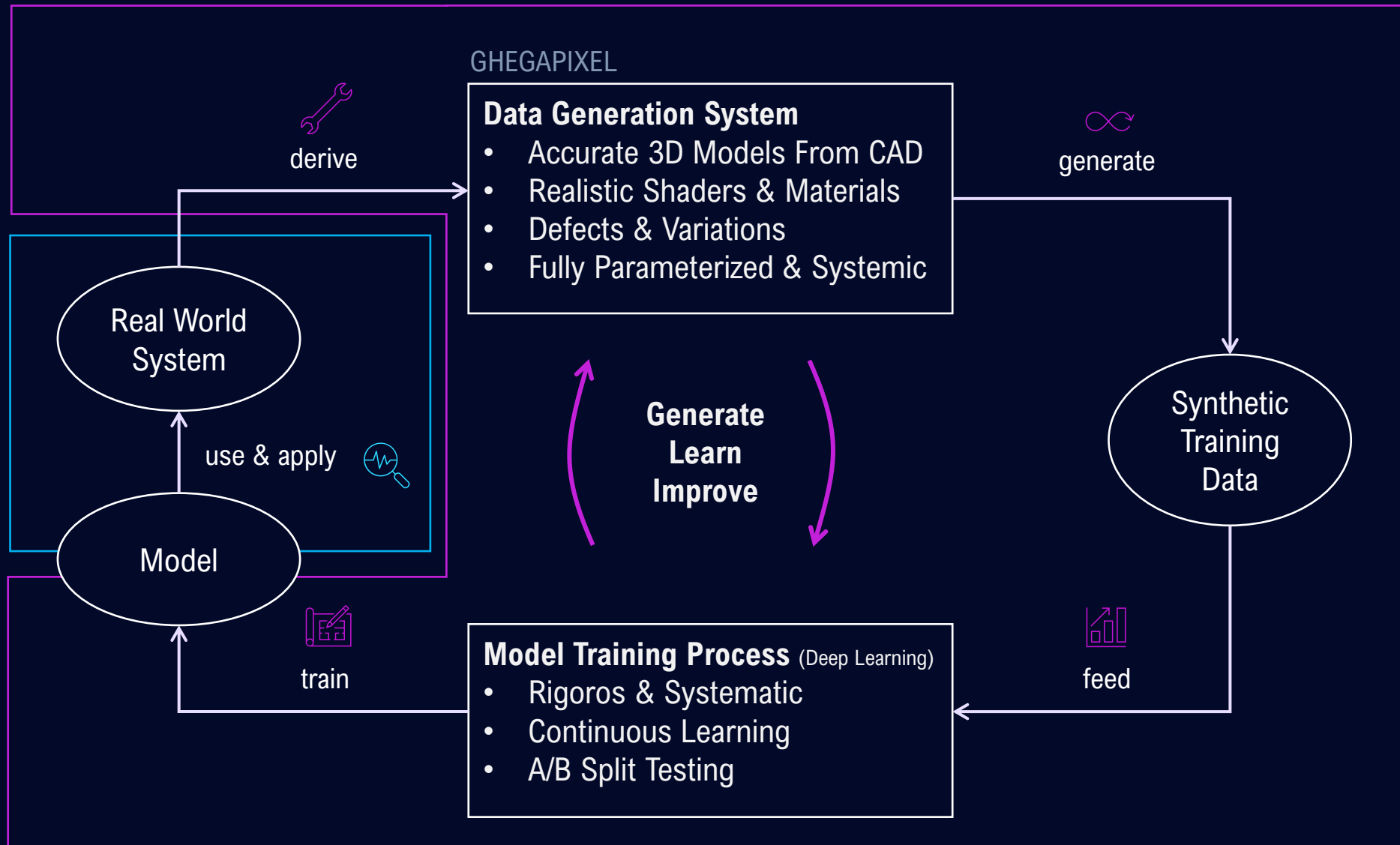
-nihilo

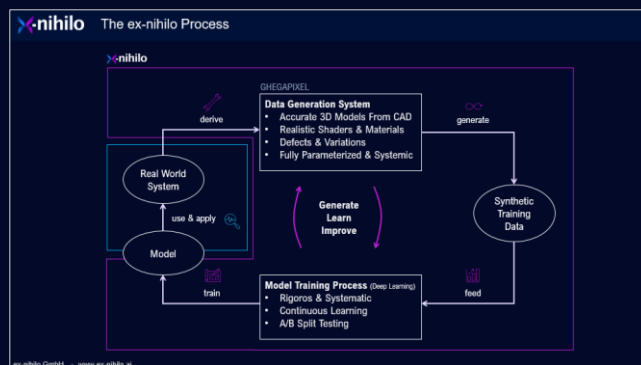
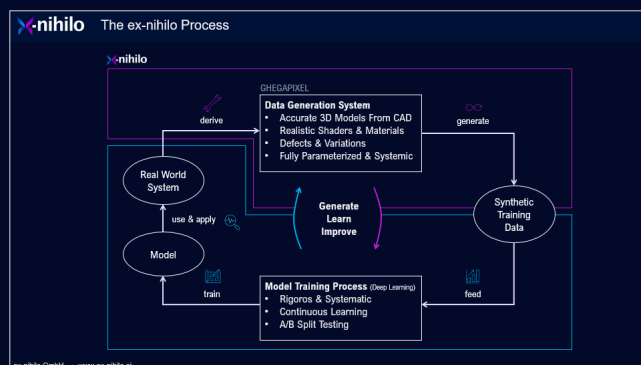
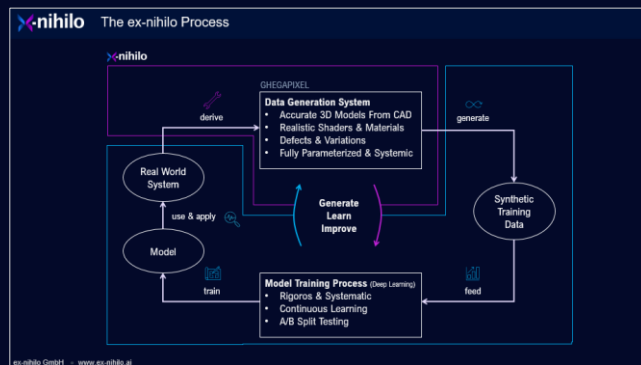


-nihilo



-nihilo





No Matter Which We Chose

All artifacts (Training Data, Metadata, Annotation, Models, Reports, etc.) can always be delivered by ex-nihilo to you

We will also make sure our results are reproducible by you

ex-nihilo needs Access to

All relevant CAD Drawings for Creating 3D Representations of the Track Structure

Reference Data Representing Real-World Component Appearances by the Imaging System

System Parameters of the Imaging System Used to Capture the Images (Resolution, Focal Length, Placement, etc.)

Possible Project

Project Costs are Influenced by

Complexity of the imaging system that needs to be modeled

Diversity of the Superstructure Type and Tracks that shall be modelled

Number and Complexity of Defects to be modelled

Additional Deliverables (Software, Custom NN-Model Architecture, Statistical Analysis Reports, etc.)

NO Influence on the Project Costs have

The Amount of Training Data needed

The Number of Generate → Learn → Improve - Iterations

Simple Project

- ✓ Little to Medium Adaptions to Ghegapixel
 - Shaders and Materials can be reused
 - Standard Defect Type (missing, fractured, misaligned)
 - New Superstructure Type to be modeled
 - Modeled Imaging System needs small adaptations
- ✓ Off The Shelf NN-Model
 - An existing NN-Architecture (e.g. YOLOv8) is sufficient
- ✓ Datasets are created by ex-nihilo and delivered regularly
- ✓ Some Edge-Cases, where detection is less accurate can be accepted for an initial solution

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Phase 1 **Proof of Concept**

3-5 months

Demonstrate the viability of the ex-nihilo process by solving detection tasks using synthetic training data. Through experimentation and validation, this phase confirms that the concept is not only feasible but also lays the foundation for further development.

Phase 2 **Deep Refinement**

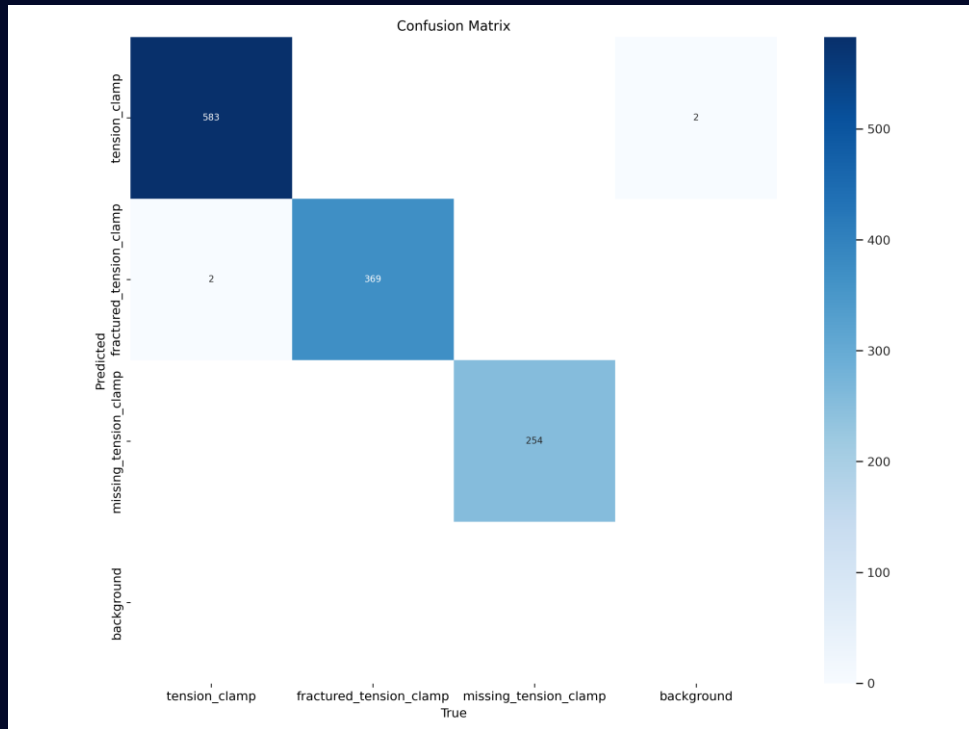
4-6 months

Here ex-nihilo commits to a deep refinement process. Building upon Phase 1, this stage focuses on making substantial improvements to the data generation. The goal is to tackle special problems and address **a wide array of edge cases**. This phase aims to elevate the solution's robustness and adaptability to even more real-world challenges.

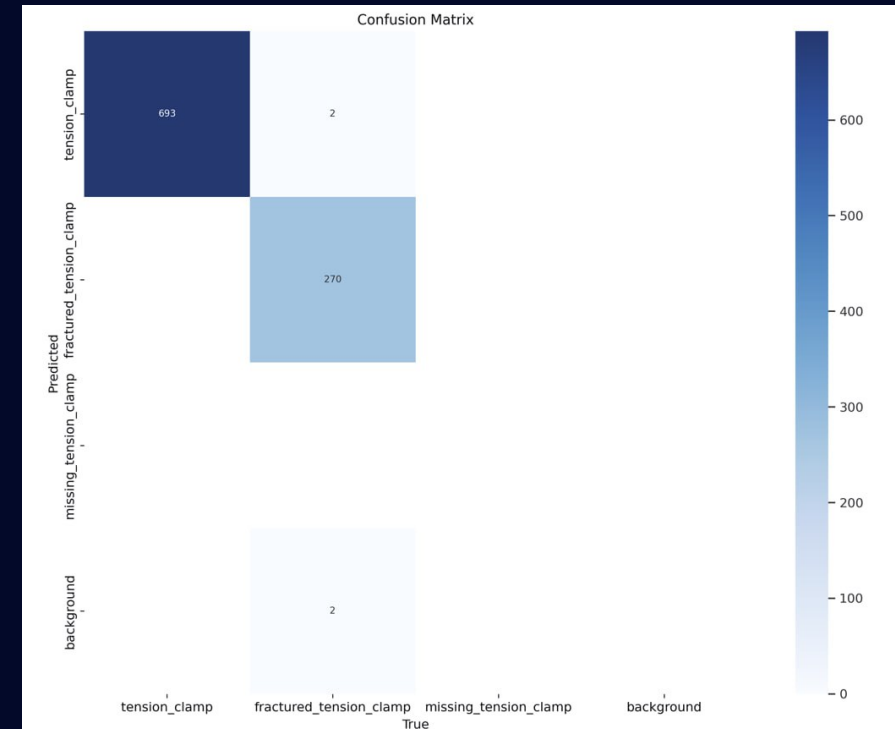
Why it Works

Let's look at a model trained by ex-nihilo

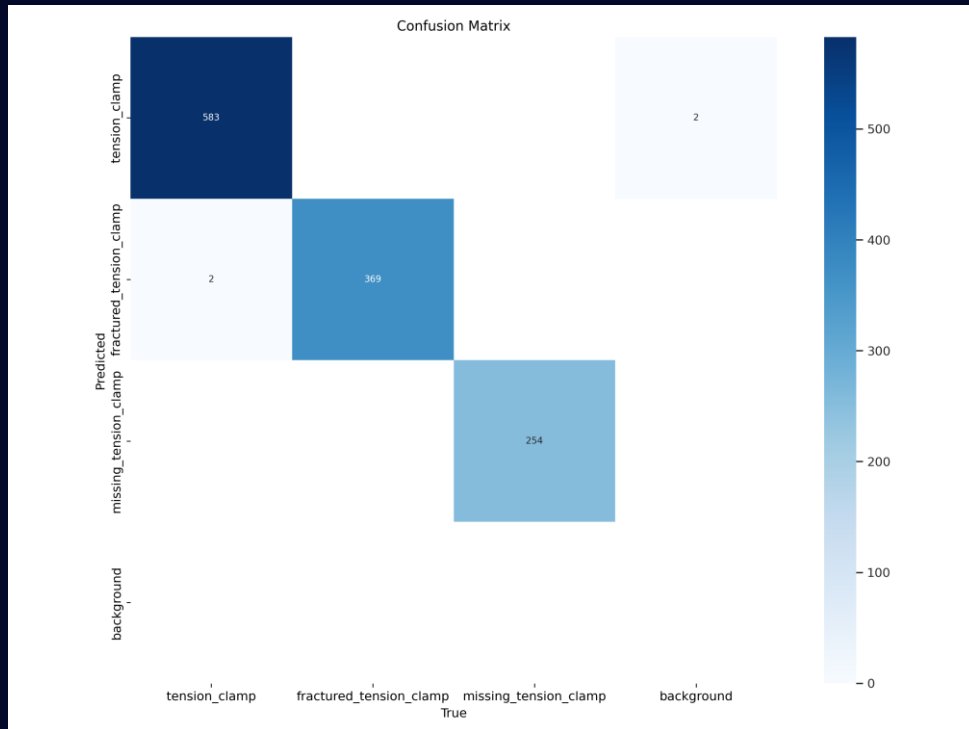
Real & Synthetic mixed



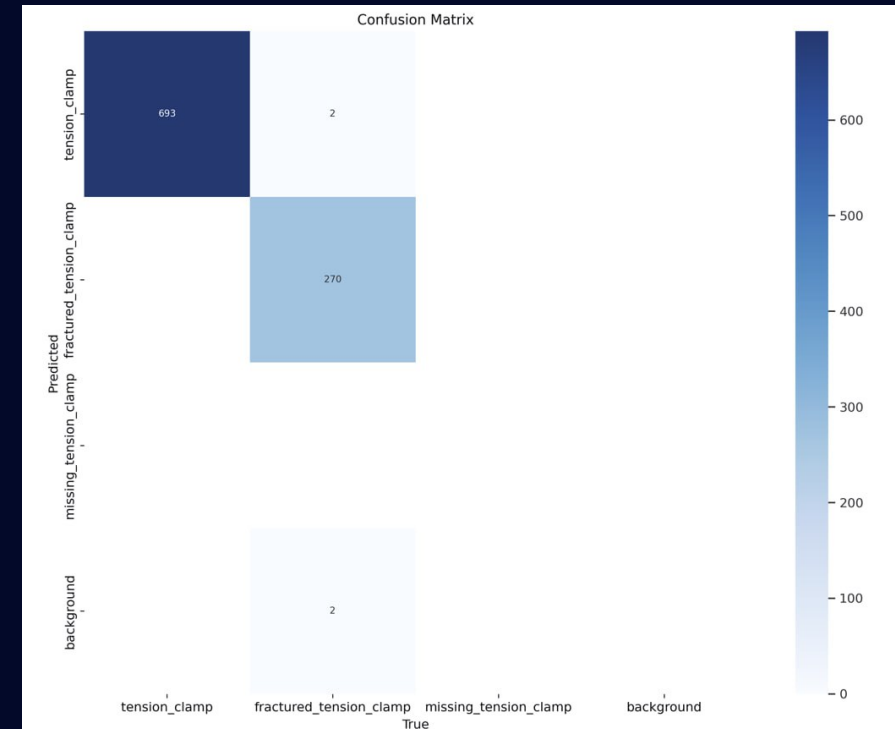
Real only (no missing)



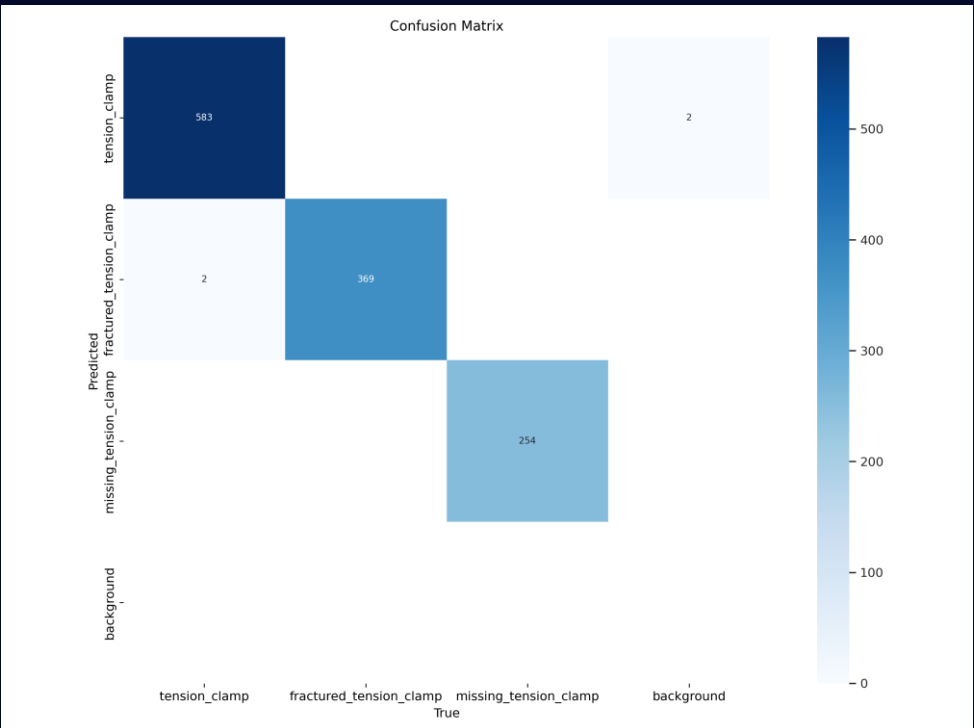
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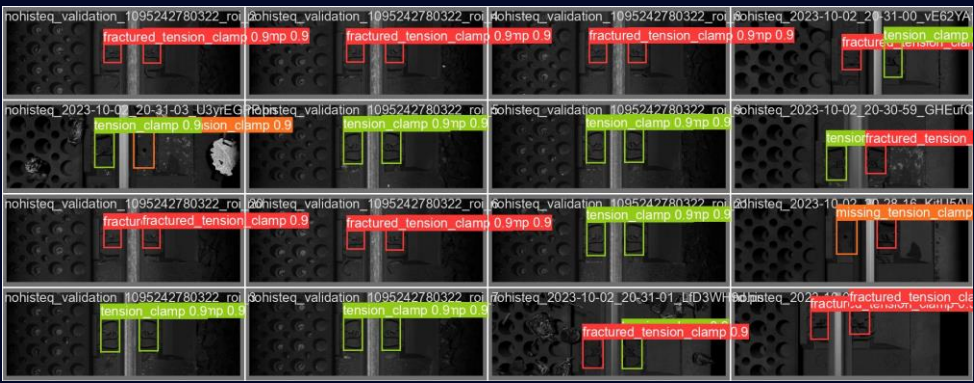
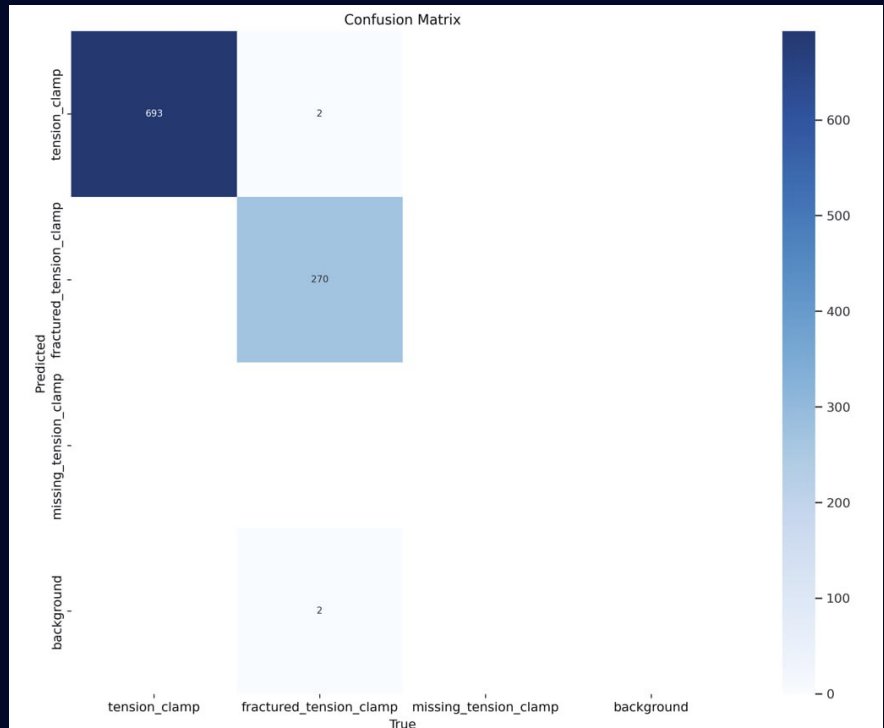
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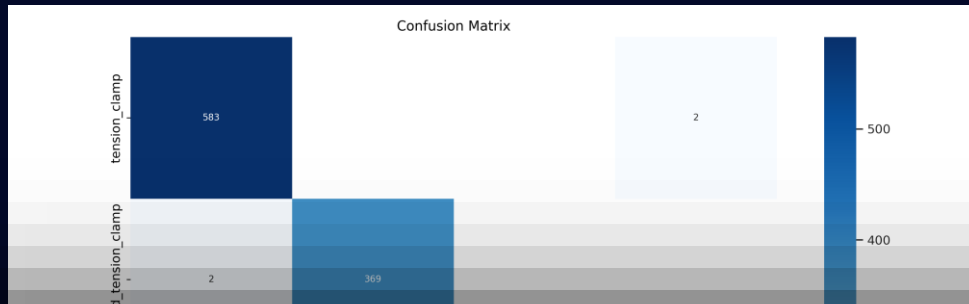
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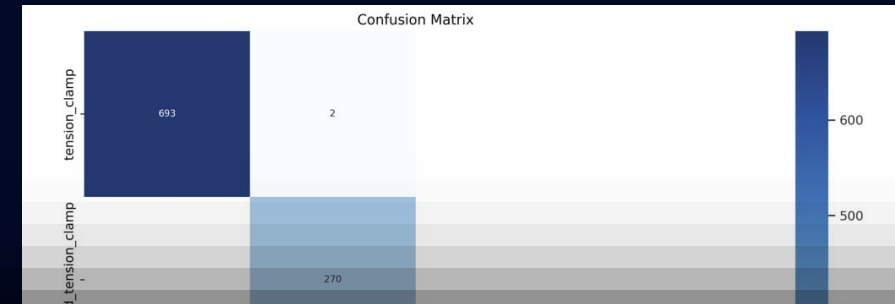
Real only (no missing)



Real & Synthetic mixed




Real only (no missing)



Trained On Synthetic Data Only

This model trained exclusively on synthetic data is the most accurate model for detecting fractured and missing tension clamps ever tested by our customer.




 Example


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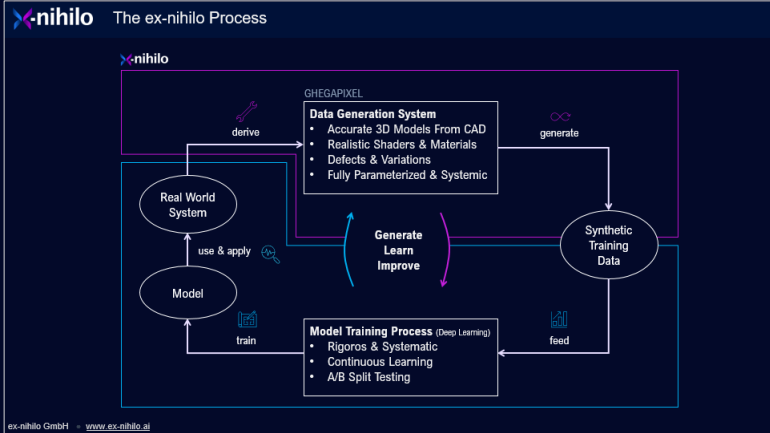
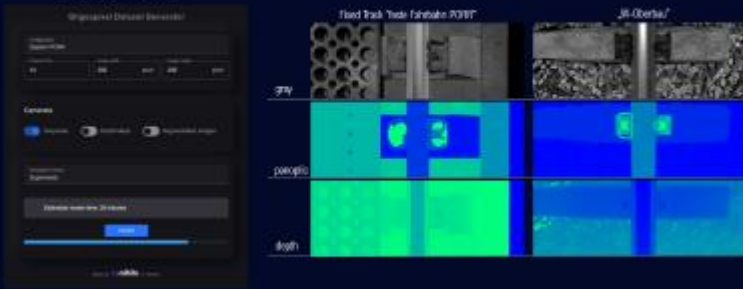
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In-House Software "Ghegapix"



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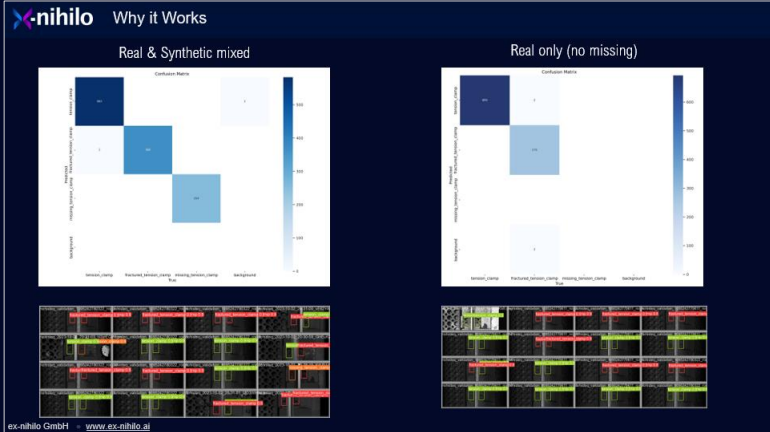
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